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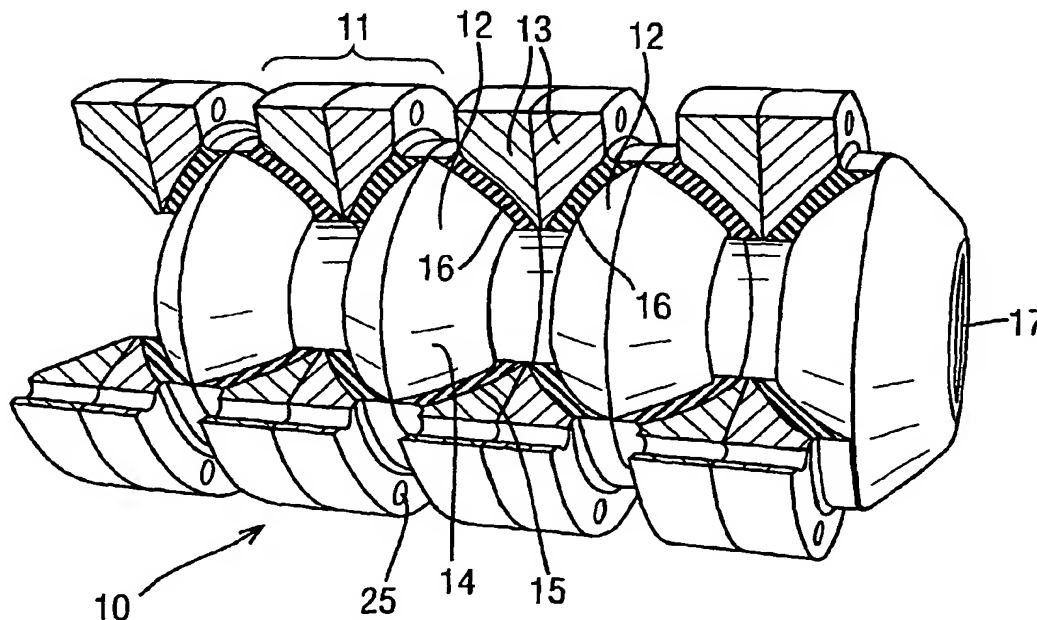
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(54) Title: LINK ASSEMBLY FOR A SNAKE LIKE ROBOT ARM



(57) Abstract: The present invention relates to a link assembly for a robot arm which arm comprises first (12) and second link (13) members each adapted for limited movement one with respect to the other and resilient elastomer means (16) disposed between said first (12) and second (13) members and bonded or keyed thereto whereby movement between the first (12) and second (13) member results in shear movement within the elastomer means disposed therebetween.